

CBIR for hyperspectral images

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Outline

1 Introduction

- Hyperspectral images
- CBIR systems

2 Feature Characterization

- Endmember induction and unmixing
- Information quantification

3 CBIR system for hyperspectral images

- Queries
- Retrieval

4 Experiment

- Design
- Results
- Conclusions

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AVIRIS cube

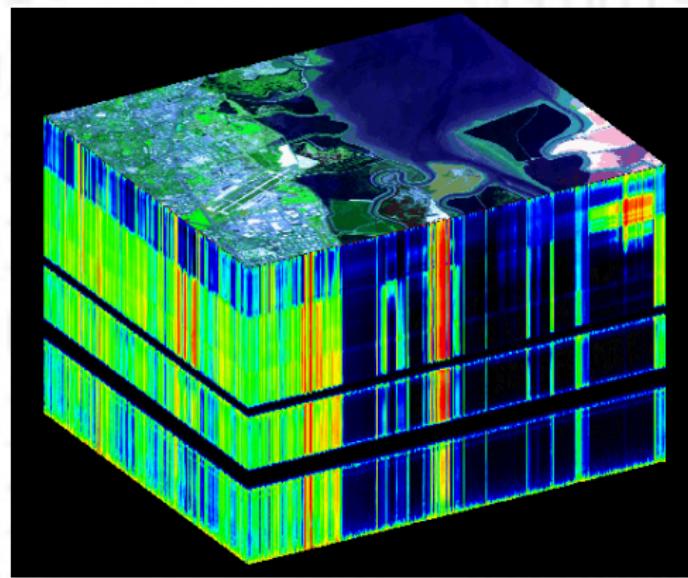
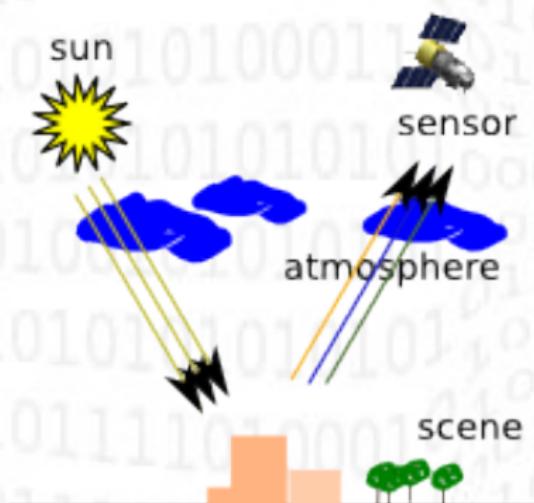


Figure: Imagen tomada desde el JPL's Airborne Visible/Infrared Imaging Spectrometer volando a 20.000 metros sobre Moffett Field, California.

Hiperespectrales VS Multiespectrales

- Número de bandas:
 - Color/Multiespectrales: 3-10 bandas.
 - Hiperespectrales: >100.
 - Resolución espectral: longitud de onda/ancho de banda
 - Color/Multiespectrales: orden de 10.
 - Hiperespectrales: orden de 100.
 - Contigüidad:
 - Color/Multiespectrales: muestreos irregulares del espectro.
 - Hiperespectrales: muestreos regulares del espectro.

Sistemas de imagen hiperespectrales

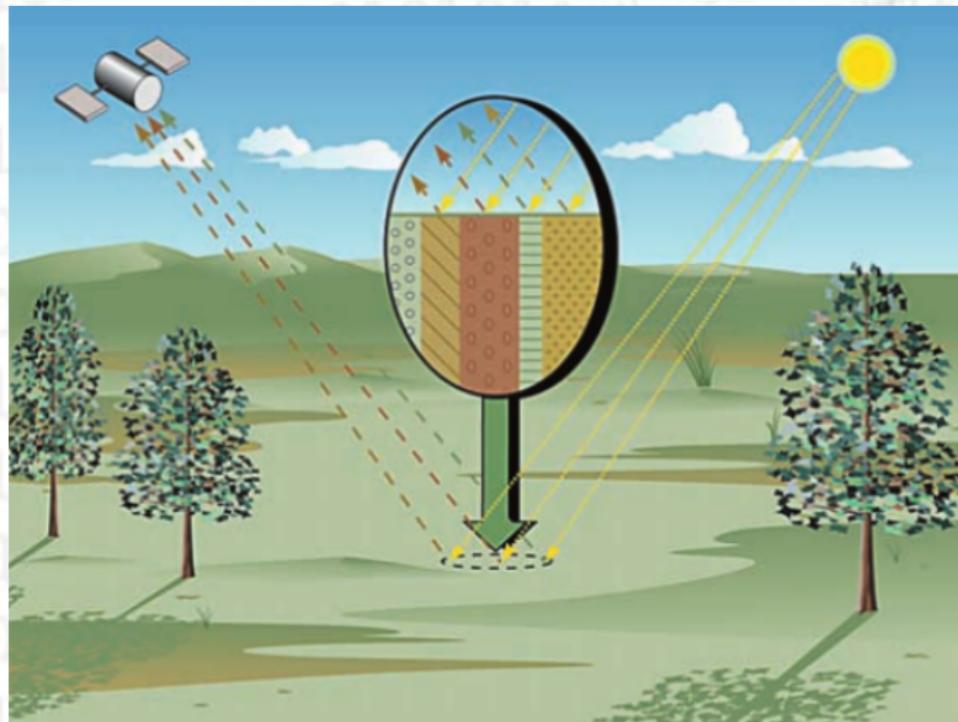


Información espacial/espectral

- Información espacial:
 - Cada pixel representa un espacio determinado de la escena.
 - Depende de la altitud y apertura del sensor.
- Información espectral:
 - Se obtiene mediante un interferómetro o prisma.
 - Un conversor convierte la radiancia muestreada en cada señal espectral.

Modelo de mezcla lineal

Ilustración



Modelo de mezcla lineal

Formulación

LMM

- $H = A \cdot E + \eta$
- $\mathbf{h}(\mathbf{x}, \mathbf{y}) = a(x, y)_1 \cdot \mathbf{e}_1 + a(x, y)_2 \cdot \mathbf{e}_2 + \dots + a(x, y)_p \cdot \mathbf{e}_p + \eta$

donde:

- H es una imagen hiperespectral con dimensiones espaciales $m \times n$ y con d bandas espectrales.
- A es una imagen de abundancias espectrales con dimensiones espaciales $m \times n$.
- E es un conjunto de p firmas espectrales (endmembers) con d bandas.
- η es ruido aditivo.

Modelo de mezcla lineal

Restricciones

LMM

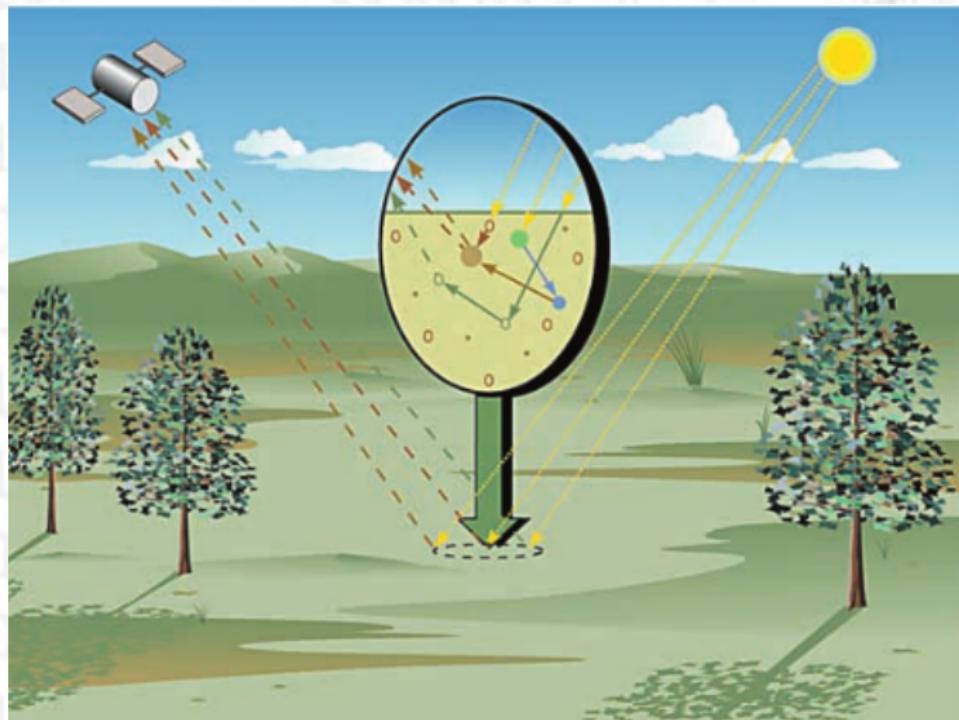
- $H = A \cdot E + \eta$
- $\mathbf{h}(\mathbf{x}, \mathbf{y}) = a(x, y)_1 \cdot \mathbf{e}_1 + a(x, y)_2 \cdot \mathbf{e}_2 + \dots + a(x, y)_p \cdot \mathbf{e}_p + \eta$

sujeto a:

- Abundance Non-negative Constraint (ANC): $a(x, y)_i \geq 0$
- Abundance Sum-to-one Constraint (ASC): $\sum_i a(x, y)_i = 1$

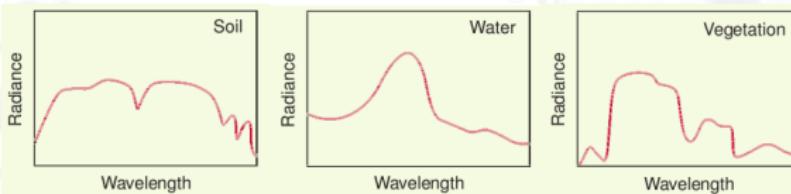
Modelo de mezcla no lineal

Ilustración



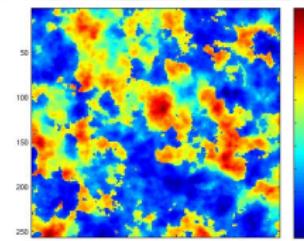
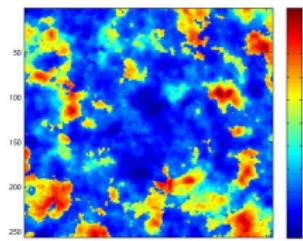
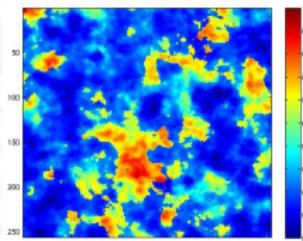
Endmembers

- Firmas espectrales de distintos materiales a una escala, resolución y frecuencias dadas.
- USGS library: firmas espectrales de multitud de materiales obtenidas mediante técnicas de espectroscopía con microscopios en laboratorio.



Imágenes de abundancia

- Indican la proporción de cada material en la imagen.
- Información espacial.



Demezclado (Unmixing)

- Obtener las imágenes de abundancia a partir de la imagen hiperespectral original y un conjunto de firmas espectrales (endmembers).
- Estimación mediante mínimos cuadrados (Least-Squares Estimation).

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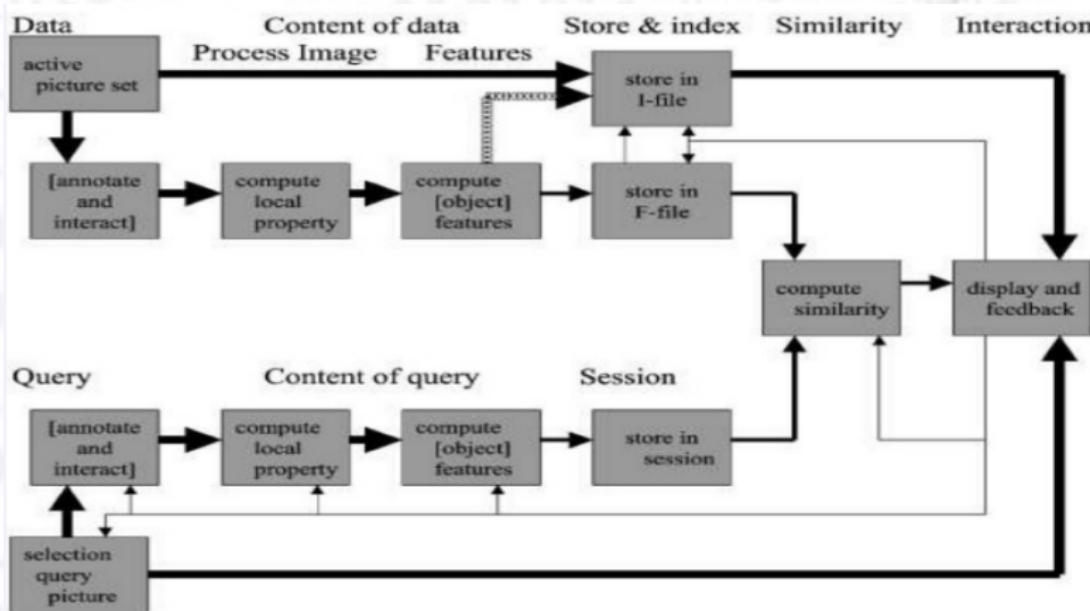
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Objetivos

- Recuperar información de grandes bases de datos (imágenes).
- Superar las deficiencias de los métodos tradicionales basados en metadatos.
- Usar la información contenida en las imágenes como base para las búsquedas.
- Elaboración de métricas basadas en la caracterización de la información contenida en las imágenes.

Descripción



* From "Content-Based Image Retrieval at the end of the early years". W.M.Smeulder et al., IEEE Trans. on Pattern Analysis and Machine Intelligence (2000)

Retrieval feedback

- Salto semántico: existe una brecha entre la información semántica buscada por el usuario y la caracterización de la información de las imágenes.
- Especialmente importante en dominios amplios (variabilidad del catálogo de imágenes).
- Retrieval feedback: proceso iterativo por el cual el usuario refina la búsqueda en función de los resultados previos (selección de resultados positivos y negativos).

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Endmember induction

- Induce the set of endmembers that generates the hyperspectral image.
- It must be an automatic and, desirably, a fast process.
- Different methodologies: geometrical, heuristics, morphological, ...
- More or less, they all follow the linear mixing model.

Unmixing

- Extract the abundancies of each endmember in the hyperspectral image.
- Different methods depending on the restrictions to the model and the provided information about the endmembers.

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Feature vector

- The feature vector describing an hyperspectral image is defined by:
 - A set of endmembers.
 - The abundance images of each endmember.
- The number of features for each image is variable: each image has a different number of endmembers.
- The spatial information can be given as parametric models (MRF) or statistical variables (mean, variance, kurtosis, ...).

Methodologies

- Endmember induction:
 - Virtual dimensionality methods: helps to tune the induction method.
 - Morphological methods: fast and automatic.
- Abundance extraction:
 - Least Squares method.
 - Full-Constrained Least Squares method.
- Modelling occurrence and spatial information:
 - Statistics: mean, variance, kurtosis, ...
 - Markov Random Fields.

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Spectral queries

- Images containing a set of specific endmembers: $Q = \{E_i\}_{i=1}^n$.
- Images containing a set of specific endmembers and not containing a distinct set of specific endmembers:
 $Q = \{E_i\}_{i=1}^n \cup \neg \{E_j\}_{j=1}^m$, where $E_i \neq E_j, \forall i, j$.

Spectral/Spatial queries

- Images containing a set of specific endmembers with a determined spatial distribution: $Q = \{(E_i, A_i)\}_{i=1}^n$.

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System definition

- The user defines the query by a set of positive or negative images.
- The system extracts the features: endmembers and abundancies (denoted as samples).
- The system compares the query features with the features of the database images and establishes a similarity ordered list, S .
- The system presents to the user the $k > 0$ first images of S , denoted by S_k .
- The user selects positive and negative images from the set S_k .
- The system redefines the query by adding the relevance information provided by the user.

Only positive samples

- When the query is defined only as a set of positive samples.
- Model the positive class and retrieve the images with higher probability of being an occurrence of the modelled class.
- Kernel One-Class Support Vector Machine (KOC-SVM) [5].

Positive and negative samples

- The query is defined as a set of positive and negative samples.
- The positive samples form a well defined class.
- The negative samples form a very heterogeneous group that cannot be modelled as a class but it gives useful information.
- Alternatives:
 - Classic two-classes SVM.
 - One-class SVM /SVDD for both positive/negative classes [5, 6].

Only negative samples

- The query is defined only as a set of negative samples.
- The desired class cannot be modelled but negative samples can be used to restrict the search.
- One-class SVM / SVDD for negative samples [6].

With occurrence probability

- The query is defined by a set of positive and/or negative samples and an associated probability distribution function for each.
- Each endmember has associated a probability of occurrence.
- Alternatives:
 - Modifications of the previous methodologies.
 - Weighted kernel density estimations.

With spatial distribution

- The query is defined by a set of positive / negative samples and abundance images associated to them.
- Each endmember has associated an abundance image.
- Alternatives:
 - Modifications of previous methodologies.
 - Model the spatial information independently (MRF).

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For Further Reading |

-  Hyperspectral Data Exploitation: Theory and Applications.
Chein-I Chang. 2007.
-  Hyperspectral Imaging: Techniques for Spectral detection and Classification. Chein-I Chang. 2003.
-  Signal Theory Methods in Multispectral Remote Sensing.
David A. Landgrebe. 2003.
-  Remote Sensing: the Image Approach, 2nd Edition. John R. Scott. 2007.
-  One-Class SVM for Learning in Image Retrieval. Yunqiang Chen, Xiang Zhou, Thomas S. Huang. Proc. IEEE Int. Conf. on Image Processing, Thessaloniki, Greece. 2001.

For Further Reading II

-  Non-Relevance Feedback Document Retrieval Based on One-Class SVM and SVDD. Takashi Onoda, Hiroshi Murata, Seiji Yamada. International Joint Conference on Neural Networks, Vancouver, Canada. 2006.

Questions?

Thank you very much for your attention.

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